

## nag\_real\_lu\_solve\_mult\_rhs (f04ajc)

### 1. Purpose

**nag\_real\_lu\_solve\_mult\_rhs (f04ajc)** calculates the approximate solution of a set of real linear equations with multiple right-hand sides,  $AX = B$ , where  $A$  has been factorized by **nag\_real\_lu** (f03afc).

### 2. Specification

```
#include <nag.h>
#include <nagf04.h>

void nag_real_lu_solve_mult_rhs(Integer n, Integer nrhs, double a[],
    Integer tda, Integer pivot[], double b[], Integer tdb, NagError *fail)
```

### 3. Description

To solve a set of real linear equations  $AX = B$ , this function must be preceded by a call to **nag\_real\_lu** (f03afc) which computes an  $LU$  factorization of  $A$  with partial pivoting,  $PA = LU$ , where  $P$  is a permutation matrix,  $L$  is lower triangular and  $U$  is unit upper triangular. The columns  $x$  of the solution  $X$  are found by forward and backward substitution in  $Ly = Pb$  and  $Ux = y$ , where  $b$  is a column of the right-hand sides.

### 4. Parameters

**n**

Input:  $n$ , the order of the matrix  $A$ .  
Constraint:  $\mathbf{n} \geq 1$ .

**nrhs**

Input:  $r$ , the number of right-hand sides.  
Constraint:  $\mathbf{nrhs} \geq 1$ .

**a[n][tda]**

Input: details of the  $LU$  factorization, as returned by **nag\_real\_lu** (f03afc).

**tda**

Input: the second dimension of the array **a** as declared in the function from which **nag\_real\_lu\_solve\_mult\_rhs** is called.  
Constraint:  $\mathbf{tda} \geq \mathbf{n}$ .

**pivot[n]**

Input: details of the row interchanges as returned by **nag\_real\_lu** (f03afc).

**b[n][tdb]**

Input: the  $n$  by  $r$  right-hand side matrix  $B$ .  
Output:  $B$  is overwritten by the solution matrix  $X$ .

**tdb**

Input: the second dimension of the array **b** as declared in the function from which **nag\_real\_lu\_solve\_mult\_rhs** is called.  
Constraint:  $\mathbf{tdb} \geq \mathbf{nrhs}$ .

**fail**

The NAG error parameter, see the Essential Introduction to the NAG C Library.

### 5. Error Indications and Warnings

**NE\_INT\_ARG\_LT**

On entry, **n** must not be less than 1:  $\mathbf{n} = \langle value \rangle$ .  
On entry, **nrhs** must not be less than 1:  $\mathbf{nrhs} = \langle value \rangle$ .

**NE\_2\_INT\_ARG\_LT**

On entry, **tda** = *<value>* while **n** = *<value>*. These parameters must satisfy **tda** ≥ **n**.

On entry, **tdb** = *<value>* while **nrhs** = *<value>*. These parameters must satisfy **tdb** ≥ **nrhs**.

**6. Further Comments**

The time taken by the function is approximately proportional to  $n^2r$ .

**6.1. Accuracy**

The accuracy of the computed solutions depends on the conditioning of the original matrix. For a detailed error analysis see Wilkinson and Reinsch (1971) p 106.

**6.2. References**

Wilkinson J H and Reinsch C (1971) *Handbook for Automatic Computation (Vol II, Linear Algebra)* Springer-Verlag pp 93–110.

**7. See Also**

nag\_real\_lu (f03afc)  
nag\_real\_lin\_eqn (f04arc)

**8. Example**

To solve the set of linear equations  $AX = B$  where

$$A = \begin{pmatrix} 33 & 16 & 72 \\ -24 & -10 & -57 \\ -8 & -4 & -17 \end{pmatrix}$$

and

$$B = \begin{pmatrix} -359 \\ 281 \\ 85 \end{pmatrix}.$$

**8.1. Program Text**

```

/* nag_real_lu_solve_mult_rhs(f04ajc) Example Program
 *
 * Copyright 1990 Numerical Algorithms Group.
 *
 * Mark 1, 1990.
 */

#include <nag.h>
#include <stdio.h>
#include <nag_stdlib.h>
#include <nagf03.h>
#include <nagf04.h>

#define TDB 3
#define NMAX 8
#define TDA NMAX

main()
{
    double detf;
    Integer i, dete, j, n, nrhs = 1;
    double a[NMAX][TDA], b[NMAX][TDB];
    Integer pivot[NMAX];
    static NagError fail;

```

```

Vprintf("f04ajc Example Program Results\n");
/* Skip heading in data file */
Vscanf("%*[^\\n]");
Vscanf("%ld",&n);
if (n>0 && n<=NMAX)
{
  for (i=0; i<n; i++)
    for (j=0; j<n; j++)
      Vscanf("%lf",&a[i][j]);
  /* Crout decomposition */
  fail.print = TRUE;
  f03afc(n,(double *)a,(Integer)TDA,pivot,&detf,&dete,&fail);
  if (fail.code!=NE_NOERROR)
    exit(EXIT_FAILURE);
  else
  {
    for (i=0; i<n; i++)
      for (j=0; j<nrhs; j++)
        Vscanf("%lf",&b[i][j]);
    /*
     * Approximate solution of linear equations
     */
    f04ajc(n,nrhs,(double *)a,(Integer)TDA,pivot,(double *)b,
      (Integer)TDB,&fail);
    if (fail.code!=NE_NOERROR)
      exit(EXIT_FAILURE);
    Vprintf("Solution\n");
    for (i=0; i<n; i++)
      for (j=0; j<nrhs; j++)
        Vprintf("%9.4f\\n",b[i][j]);
  }
}
else
{
  Vfprintf(stderr, "N is out of range: N = %5ld\\n", n);
  exit(EXIT_FAILURE);
}
exit(EXIT_SUCCESS);
}

```

## 8.2. Program Data

```

f04ajc Example Program Data
3
 33  16  72
-24 -10 -57
  -8  -4 -17
-359 281  85

```

## 8.3. Program Results

```

f04ajc Example Program Results
Solution
 1.0000
-2.0000
-5.0000

```

---